integral balance control domain physical domain flux

Chapter 1

Integral Balances

 $\overline{\mathcal{G}}^{(1)}$

Let \mathcal{F} be a tensor field of order *n* for which we want to write the **integral** balance over a domain.

1. There will be two cases depending on whether the domain is

- A geometric control domain D that is fixed relative to the referential,
- A frozen, **physical domain** \hat{D} that we follow in its motion.
- 2. Given a tensor field $\overline{\mathcal{I}}^{\odot}$, we define the tensor fields

$$\overline{\mathcal{G}}^{\odot} = \iiint \overline{\mathcal{G}}^{\odot} dv$$
$$\overline{\mathcal{F}}^{\odot} = \iiint \overline{\mathcal{G}}^{\odot} \otimes U \cdot nds \qquad \text{(The flux of the tensor field } \overline{\mathcal{G}}^{\odot}\text{)}$$

where the integrals are taken, depending on the case, on D, S or ${\cal D}$

3. Depending on whether the domain is a geometric control domain or a frozen physical domain, we will have to evaluate the following quantity:

• In the case of a geometric control domain,

$$\frac{d}{dt}\overline{\mathcal{G}}^{\otimes}{}_{D} + \overline{\mathcal{F}}^{\otimes}{}_{S}$$

• In the case of a frozen physical domain

$$\frac{D}{Dt}\overline{\mathcal{G}}^{\textcircled{0}}$$

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